

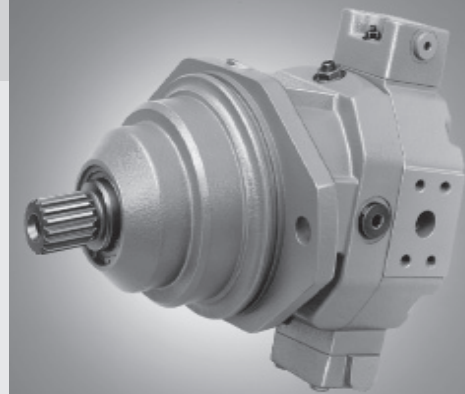
Variable Displacement Plug-In Motor A6VE

RE 91 606/06.05 1/16
Replaces: 05.99

Technical data sheet

Series 6

Sizes	Nominal pressure / Peak pressure
28 ... 160	400 / 450 bar
250	350 / 400 bar
open and closed circuits	



Contents

Ordering Code / Standard Program	2
Technical Data	4
Unit Dimensions	6
Port Plate 22 with Integr. Counterbalance	8
Flushing and Boost Pressure Valve	10
Speed Measurement	11
Connectors for Solenoid (for EP, EZ only)	12
Installation and Commissioning Notes	13
Project Sheet	14
General Notes	16

Features

- Variable displacement plug-in motor with a axial tapered piston rotary group of bent axis design for hydrostatic drives in open and closed circuits
- Easy assembly, simply «plugs-in» to mechanical gearboxes (no installation tolerances to consider)
- The design of the motor with the mounting flange in the centre of the housing allows it to be almost fully integrated into a mechanical gearbox to give an extremely compact unit.
- For use in mobile applications
- Ready assembled and tested unit
- The displacement is continuously variable from $V_{g \max}$ to $V_{g \min} = 0$.
- The output speed depends on the flow capacity of the pumps and the displacement of the motor.
- The torque increases with the pressure differential between the high and low pressure side and with increasing displacement.
- Further informations:

Variable displacement motor A6VM

RE 91 604

Ordering Code / Standard Program

A6V	E					/	6	3	W	-	V									
01	02	03	04	05	06		07	08	09	10		11	12	13	14	15	16	17	18	19

Axial piston units

01	Bent-axis type, variable	A6V
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Mode of operation

02	Motor, plug-in version	E
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Size

03	≈ Displacement $V_{g \max}$ in cm^3	28	55	80	107	160	250
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Control device

			28	55	80	107	160	250	
04	Hydraulic control, pilot pressure related	$\Delta p = 10 \text{ bar}$ HD1	●	●	●	●	●	●	HD1
		$\Delta p = 25 \text{ bar}$ HD2	●	●	●	●	●	●	HD2
	Hydraulic two-point control	HZ	-	-	-	-	-	●	HZ
		HZ1	●	-	-	-	●	-	HZ1
		HZ3	-	●	●	●	● ¹⁾	-	HZ3
	Electrical control, with proportional solenoid	12 V EP1	●	●	●	●	●	●	EP1
24 V EP2		●	●	●	●	●	●	EP2	
12 V EZ1		●	-	-	-	●	●	EZ1	
24 V EZ2		●	-	-	-	●	●	EZ2	
Electrical two-point control, with solenoid	12 V EZ3	-	●	●	●	-	-	EZ3	
	24 V EZ4	-	●	●	●	-	-	EZ4	
	Automatic control, high pressure related	without pressure increase HA1	●	●	●	●	●	●	HA1
		pressure increase $\Delta p = 100 \text{ bar}$ HA2	●	●	●	●	●	●	HA2
without pressure increase HA3		-	●	●	●	●	-	HA3 ¹⁾	
Hydraulic control, speed related	$p_{St}/p_{HD} = 3/100$, hydraulic travel direction valve DA	-	-	-	-	-	●	DA	
	$p_{St}/p_{HD} = 5/100$, el. travel direction valve + el. $V_{g \max}$ switch (24V) DA3	●	●	●	●	●	-	DA3	

Pressure cut off (for HD, EP)

05	without pressure cut off (no code)	
	with pressure cut off, direct	D

Overriding HA control

06	without override (no code)	
	with override, hydraulic	T

Series

07		6
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Index

08		3
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Direction of rotation

09	viewed on shaft end, alternating	W
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Setting range for displacement ²⁾

		28	55	80	107	160	250	
10	$V_{g \min} = 0$ to $0,8 V_{g \max}$ (no code)	●	●	●	●	●	-	
	$V_{g \min} = 0$ to $0,4 V_{g \max}$ $V_{g \max} = V_{g \max}$ to $0,8 V_{g \max}$	-	-	-	-	-	●	1
	$V_{g \min} > 0,4 V_{g \max}$ to $0,8 V_{g \max}$ $V_{g \max} = V_{g \max}$ to $0,8 V_{g \max}$	-	-	-	-	-	●	2

¹⁾ only possible in connection with port plate 22 (integral motion control valve)

²⁾ Note: $V_{g \min}$ and $V_{g \max}$ are infinitely adjustable in the adjustment ranges.

Please specify precise values in plain text when placing your order: $V_{g \min} = \dots \text{ cm}^3$, $V_{g \max} = \dots \text{ cm}^3$.

Ordering Code / Standard Program

A6V	E					/	6	3	W		-	V								
01	02	03	04	05	06		07	08	09	10		11	12	13	14	15	16	17	18	19

		Seals							
		28	55	80	107	160	250		
11	FKM (fluor-caoutchouc)	●	●	●	●	●	●	V	

		Shaft end							
12	Splined shaft DIN 5480	●	-	●	-	●	-	A	
		-	●	-	●	-	●	Z	

		Mounting flange							
		28	55	80	107	160	250		
13	2-hole, similar to ISO 3019-2	●	●	●	●	●	-	L	
	4-hole, similar to ISO 3019-2	-	-	-	-	-	●	M	
	2-hole (Modified adaption flange)	-	-	-	●	-	-	U	

		Service line connections ³⁾								
14	Ports A, B: SAE side, opposite	02	0	●	●	●	●	●	●	020
			7	●	●	●	●	●	●	027
	Port plate with integr. counterbalance valve (with brake release valve) and secondary valve (port A, B: SAE side, same side)	22	1	-	●	●	●	●	-	221 ⁴⁾
			2	-	●	●	●	●	-	222 ⁴⁾

		Valves	
15	without valve		0
	Brake release valve (pilot pressure for brake release)	internal boring	1
		external piping	2
	with flushing and boost pressure valve		7

		Speed measurement							
		28	55	80	107	160	250		
16	without speed measurement (no code)	●	●	●	●	●	●		
	prepared for speed measurement (HDD) ⁵⁾	●	●	●	●	●	-	F	

		Connectors for solenoids (sizes 28...160 only)								
17	DEUTSCH DT04-2P-EP04	injection molded	EP1/2	●	●	●	●	●	●	P
			EZ1/2	●	-	-	-	●	●	P
	with lead	EZ3/4	-	●	●	●	-	-	-	T

		Start of control								
18	Port plate 02	at $V_{g\ min}$ (standard for HA)	●	●	●	●	●	●	A	
		at $V_{g\ max}$ (standard for HD, HZ, EP, EZ, DA)	●	●	●	●	●	●	B	
	Port plate 22	at $V_{g\ min}$ (standard for HA3)	-	●	●	●	●	-	B	
		at $V_{g\ max}$ (standard for HZ3)	-	●	●	●	●	-	B	

		Counterbalance valve code (for port plate 22 only)							
19	9-digits code (is issued from Rexroth at projection of the integral counterbalance valve)								

³⁾ fastening threads are metric

⁴⁾ only possible in combination with HZ3, HA3 control

⁵⁾ complete order recommended, speed sensor page 11

● = available ○ = in preparation - = not available

= preferred program

Technical Data

Hydraulic fluid

Before starting project planning, please refer to our data sheets RE 90220 (mineral oil), RE 90221 (environmentally acceptable hydraulic fluids) and RE 90223 (HF hydraulic fluids) for detailed information regarding the choice of hydraulic fluids and conditions of use.

The A6VE variable displacement plug-in motor is not suitable for use with HFA. If HFB, HFC and HFD or environmentally acceptable hydraulic fluids are being used, the constraints regarding technical data and seals mentioned in RE 90221 and RE 90223 must be observed.

If necessary, please contact us to discuss the type of hydraulic fluid you intend to use.

Viscosity range

We recommend that a viscosity (at operating temperature) for optimum efficiency and service life purposes of

$$v_{\text{opt}} = \text{optimum viscosity } 16 \text{ to } 36 \text{ mm}^2/\text{s}$$

be chosen, taken the circulation temperature (closed circuit) and reservoir temperature (open circuit) into account.

Limits of viscosity range

The following values apply in extreme cases:

$$v_{\text{min}} = 5 \text{ mm}^2/\text{s}$$

short-term ($t < 3$ min) at max. permitted temperature of $t_{\text{max}} = +115^\circ\text{C}$.

$$v_{\text{max}} = 1600 \text{ mm}^2/\text{s},$$

short-term ($t < 3$ min) with cold start ($p < 30$ bar, $n \leq 1000$ rpm, $t_{\text{min}} = -40^\circ\text{C}$).

Note that the maximum hydraulic fluid temperature must not be exceeded locally either (e.g. during storage). The temperature in the bearing area is - depending on pressure and speed - up to 12 K higher than the average case drain temperature.

Special measures are necessary at temperatures between -25°C and -40°C . Please contact us.

See RE 90300-03-B for detailed information about use at low temperatures.

Filtering

The finer the filtering, the cleaner the fluid and the longer the service life of the axial piston unit.

To ensure proper function of the axial piston unit, the pressure fluid must have a cleanliness level of at least

20/18/15 according to ISO 4406.

At very high hydraulic fluid temperatures (90°C to max. 115°C , not permitted for sizes 250), a purity class of at least

19/17/14 according to ISO 4406 is required.

Please contact us if these cleanliness level cannot be achieved.

Operating pressure range

Maximum pressure on port A or B (pressure data according to DIN 24312)

for sizes 28...160

Nominal pressure p_N	400 bar
Peak pressure p_{max}	450 bar
Summation pressure (press. A + press. B) p_{max}	700 bar

for size 250

Nominal pressure p_N	350 bar
Peak pressure p_{max}	400 bar
Summation pressure (press. A + press. B) p_{max}	700 bar

Please note:

These values are valid for radial force free load. With additional radial force see RE 91604.

Direction of flow

Direction of rotation	
Clockwise	Counterclockwise
A to B	B to A

Speed range

No limit to minimum speed n_{min} . If uniform motion is required, n_{min} must not be less than 50 rpm. See table on page 5 for maximum speed.

Technical Data

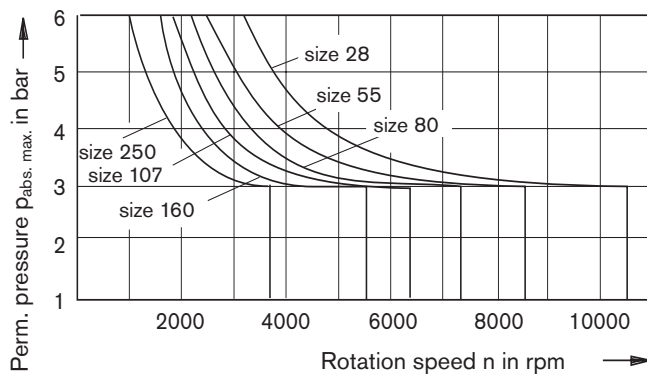
Shaft seal ring

Permissible pressure load

The service life of the shaft seal ring is affected by the speed of the motor and the case drain pressure. The permitted loading with intermittent case drain pressure depends on the rotational speed (see chart). Short-term ($t < 5$ s) pressure spikes of up to 6 bar absolute are permitted.

The average permanent case drain pressure must not exceed 3 bar absolute.

The pressure in the case must be equal to or greater than the external pressure on the shaft seal ring.



Temperature range

The FKM shaft seal ring is suitable for case temperatures of -25°C to +115°C.

Note:

For applications below -25°C a NBR shaft seal ring is necessary (admissible temperature range -40°C to +90°C). Please consult us.

Effect of case pressure on start of control

An increase in the case pressure has an effect on the following settings when control of the variable displacement motor begins:

HA1T (size 28...160)	increase
HD, EP, HA, HA.T (size 250):	increase
DA :	reduction

The start of control is set in the factory at a case pressure of $p_{abs} = 2$ bar (sizes 28 to 160) and $p_{abs} = 1$ bar (size 250).

Table of values (theoretical values, ignoring η_{mh} and η_{vi} ; values rounded)

Size			28	55	80	107	160	250	
Displacement ¹⁾	$V_{g\ max}$	cm ³	28,1	54,8	80	107	160	250	
	$V_{g\ 0}$	cm ³	0	0	0	0	0	0	
Rotation speed max. (while adhering to max. permitted flow)	n_{max} at $V_{g\ max}$	rpm	5550	4450	3900	3550	3100	2700	
	n_{max1} at $V_g < \frac{V_{g,1}}{V_{g,1}}$	rpm	8750	7000	6150	5600	4900	3600	
		cm ³	18	35	51	68	101	188	
	$n_{max\ 0}$ at $V_{g\ 0}$	rpm	10450	8350	7350	6300	5500	3600	
Flow max.	$q_{V\ max}$	L/min	156	244	312	380	496	675	
Torque max.	T_{max} at $V_{g\ max}$ ²⁾	Nm	179	349	509	681	1019	1391	
Rotary stiffness		Nm/rad	360	700	1150	1560	2320	3733	
Mass moment of inertia around output shaft	J	kgm ²	0,0014	0,0042	0,0080	0,0127	0,0253	0,061	
Filling capacity		L	0,5	0,75	1,2	1,5	2,4	3,0	
Mass (approx.)	port plate 02	m	kg	16	26	34	47	64	90
	port plate 22	m	kg	–	35	43	53	72	–

¹⁾ The minimum and maximum displacement are continuously variable, see ordering code on page 2.

(default setting size 250 unless specified in order: $V_{g\ min} = 0,2 \cdot V_{g\ max}$, $V_{g\ max} = V_{g\ max}$).

²⁾ sizes 28...160: $\Delta p = 400$ bar; size 250: $\Delta p = 350$ bar

Further informations see technical data sheet RE 91604 (variable displacement motor A6VM):

- selection diagram and details regarding the choice of hydraulic fluid
- permitted displacement and inlet pressure in relation to rotational speed
- permissible transverse and axial forces on drive shaft
- description and dimensions of displacements

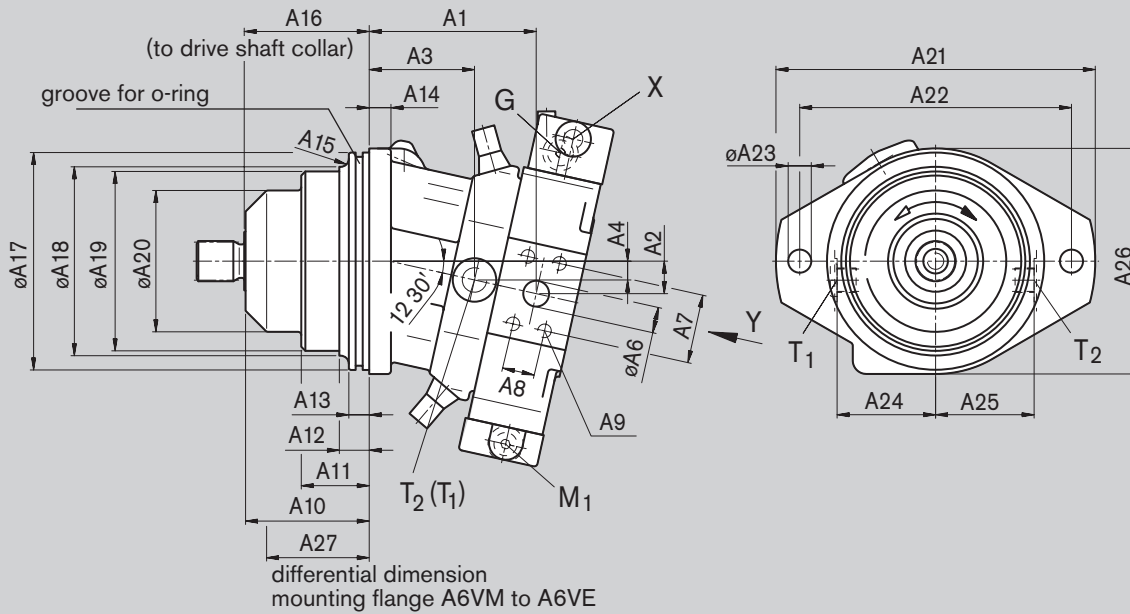
Unit Dimensions

Before finalizing your design, please request approved installation drawing. Dimensions in mm

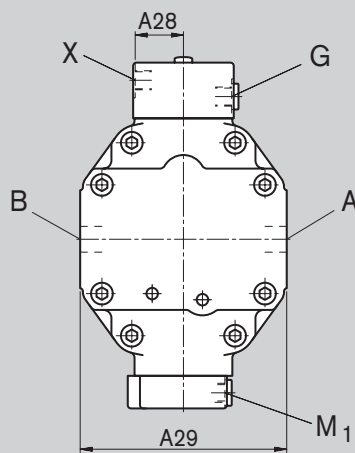
Port plate 02: SAE-ports at side

Sizes 28...160

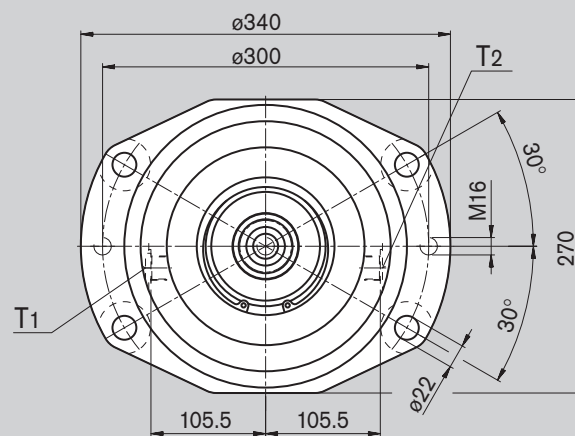
For dimensions of control devices, see technical data sheet of variable displacement motor A6VM (RE 91604)



Detail Y



Size 250



Ports

Size	Service line port A, B SAE J518	Case drain port T ₁ ; T ₂ ¹⁾ DIN 3852
28	3/4 in	M18x1,5; 12 deep 140 Nm ²⁾
55	3/4 in	M18x1,5; 12 deep 140 Nm ²⁾
80	1 in	M18x1,5; 12 deep 140 Nm ²⁾
107	1 in	M18x1,5; 12 deep 140 Nm ²⁾
160	1 1/4 in	M26x1,5; 16 deep 230 Nm ²⁾
250	1 1/4 in	M22x1,5; 14 deep 210 Nm ²⁾

¹⁾ 1x plugged ²⁾ Tightening torque, max.

Further ports see variable displacement motor A6VM (RE 91604)!

Unit Dimensions

Before finalizing your design, please request approved installation drawing. Dimensions in mm

Standard flange L (sizes 28-160), M (size 250)

Size	A1	A2	A3	A4	øA6	A7	A8	A9 (DIN 13) ¹⁾	A10	A11	A12	A13	A14	A15
28	91	20	47	10	ø19	50,8	23,8	M10x1,5; 17 deep	88	54	–	15	14	R10
55	123	24	77	14	ø19	50,8	23,8	M10x1,5; 17 deep	91	50	22	15	16	R6
80	130	28	78	16	ø25	57,2	27,8	M12x1,75; 17 deep	109,5	65	30	15	18	R10
107	137	30	84	18	ø25	57,2	27,8	M12x1,75; 17 deep	121,8	72	35	15	18	R12
160	171	34	109	20	ø32	66,7	31,8	M14x2; 19 deep	122	67	29	15	20	R5
250	204	44	103	20	ø32	66,7	31,8	M14x2; 19 deep	131,5	–	–	14	25	–

Size	A16	A17	A18	A19	A20	A21	A22	øA23	A24	A25	A26	A27	A28	A29	o-ring ²⁾
28	89	135 _{-0,025}	110	–	86	188	160	ø13,5	62,5	62,5	142	64	35,5	132	126x4
55	92	160 _{-0,025}	139	132	104	235	200	ø17	72,5	72,5	166	59	35,5	152	150x4
80	110,5	190 _{-0,029}	151	143	116	260	224	ø21	78,5	78,5	198	79	35,5	164	182x4
107	122,8	200 _{-0,029}	168	160	132	286	250	ø21	86,5	86,5	210	82	40,5	180	192x4
160	123	200 _{-0,029}	188	180	146	286	250	ø21	98,5	98,5	210	83	40,5	204	192x4
250	133,5	260 _{-0,081}	–	230	–	–	–	–	–	–	–	83,5	48,5	224	250x5

Adaption flange U (size 107)

Size	A1	A2	A3	A4	A5	A6	A7	A8	A9 (DIN 13) ¹⁾	A10	A11	A12	A13	A14
107	150	30	96	18	15,5	25	57,2	27,8	M12x1,75; 17 deep	109,5	59,7	22,7	18	15

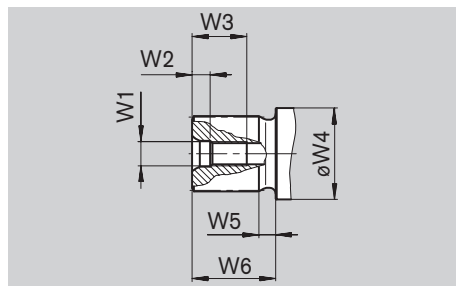
Size	A15	A16	A17	A18	A19	A20	A21	A22	A23	A24	A25	A26	A27	A28	A29	O-Ring ²⁾
107	R8	110,5	190 _{-0,025}	168	160	132	260	224	22	86,5	86,5	198	91,5	13,8	70	182x4

¹⁾ Tightening torque see general notes

²⁾ The o-ring is not included in supply

Shaft ends

Splined shaft DIN 5480

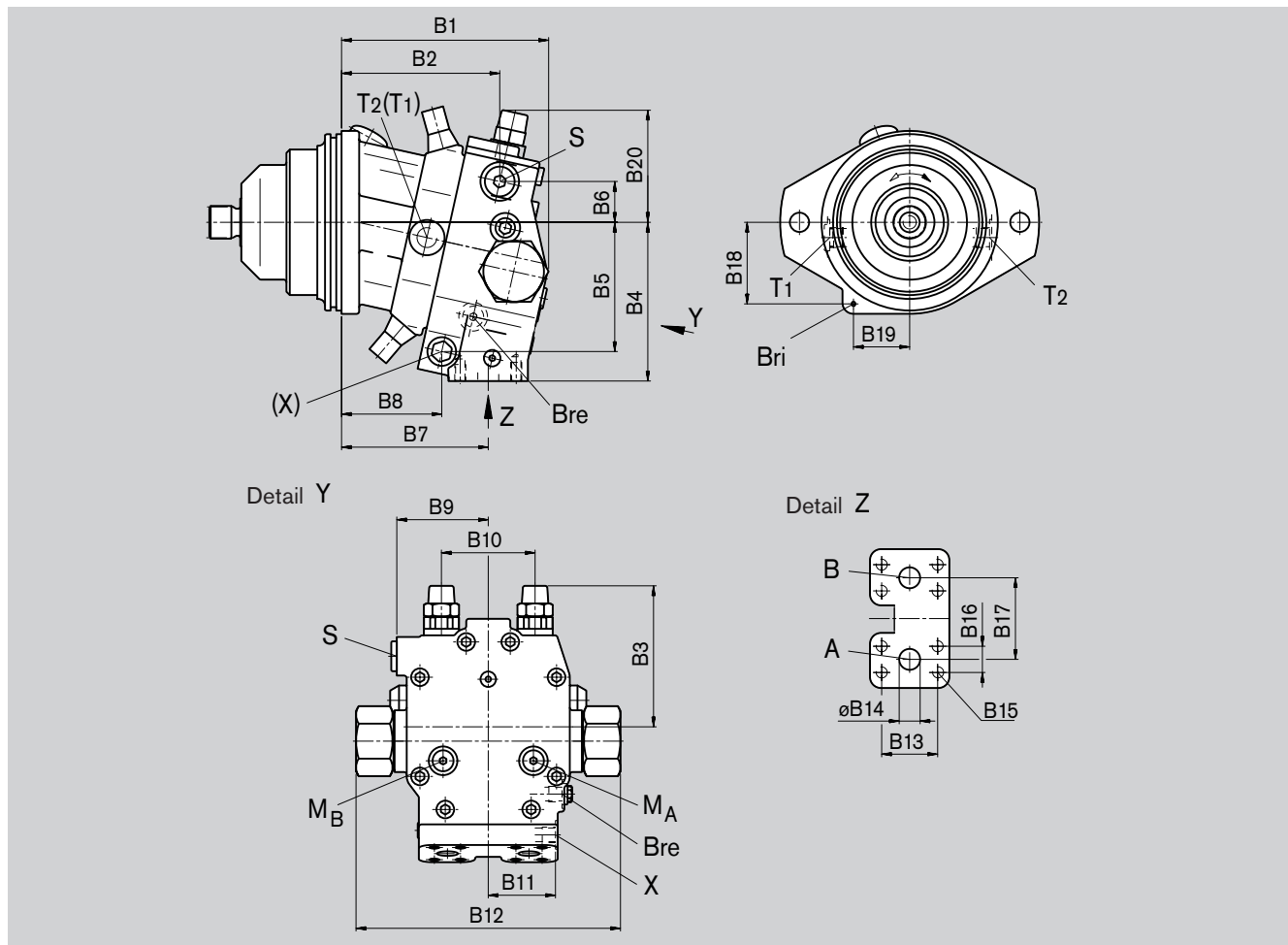


Size	Shaft end	W1	W2	W3	øW4	W5	W6
28	A (W30x2x30x14x9g)	M10	7,5	22	ø35	8	35
55	Z (W30x2x30x14x9g)	M12	9,5	28	ø45	8	35
80	A (W40x2x30x18x9g)	M16	12	36	ø50	8	45
107	Z (W40x2x30x18x9g)	M12	9,5	28	ø60	8	45
160	A (W50x2x30x24x9g)	M16	12	36	ø70	11	36
250	Z (W50x2x30x24x9g)	M16	12	36	ø60	9	58

Port Plate 22 with Integr. Counterbalance Valve

Before finalizing your design, please request approved installation drawing. Dimensions in mm

Unit dimensions



Ports

Size	B1	B2	B3	B4	B5	B6	B7	B8	B9	B10	B11	B12	B13	B14	B15 (DIN 13) ¹⁾	B16	B17
55	192	144	127	144	117	37	133	91	83	85	64	259	50,8	19	M10x1,5; 17 deep	23,8	80
80	198	150	136	162	132	40	138	93	83	90	69	259	57,2	25	M12x1,75; 17 deep	27,8	86
107	202	161	139	171,5	143	40	144	99	85	96	72	259	57,2	25	M12x1,75; 17 deep	27,8	86
160	240	195	152	197	162	47	177	128	102	108	78	259	66,7	32	M14x2; 19 deep	31,8	94

Size	B18	B19	B20	Service line port A, B SAE J518	Case drain port T ₁ ; T ₂ ²⁾ DIN 3852	Boosting S DIN 3852
55	74	51	102	3/4in	M18x1,5; 12 deep 140 Nm ³⁾	M22x1,5; 14 deep
80	90	53	114	1in	M18x1,5; 12 deep 140 Nm ³⁾	M22x1,5; 14 deep
107	96	58	122	1in	M18x1,5; 12 deep 140 Nm ³⁾	M22x1,5; 14 deep
160	94	65	136	1 1/4in	M26x1,5; 16 deep 230 Nm ³⁾	M27x2; 16 deep

¹⁾ Tightening torque see general notes

²⁾ 1x plugged

³⁾ Tightening torque, max

X	Pilot pressure port (open at HZ3 and HA3T, closed at HA3)	DIN 3852	M14x1,5; 12 deep
M _A , M _B	Measuring port	DIN 3852	M14x1,5; 12 deep
M	Measuring port for control pressure (at HA3 only)	DIN 3852	M 10x1; 8 deep
Bre	Brake released port extern (open at design 222)	DIN 3852	M14x1,5; 12 deep
Bri	Brake released port intern (not at design with flange U)		ø4

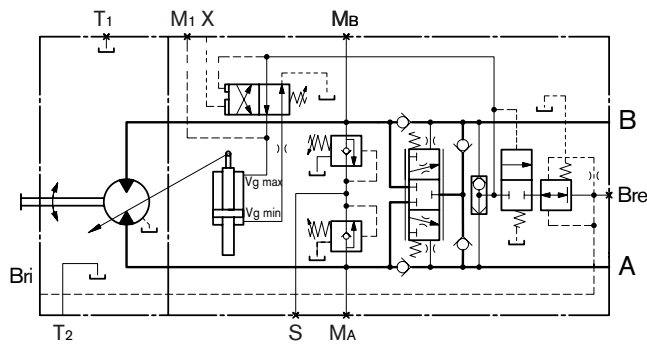
Note: Port plate HZ3 and HA3 are not identical!

Circuit Diagrams

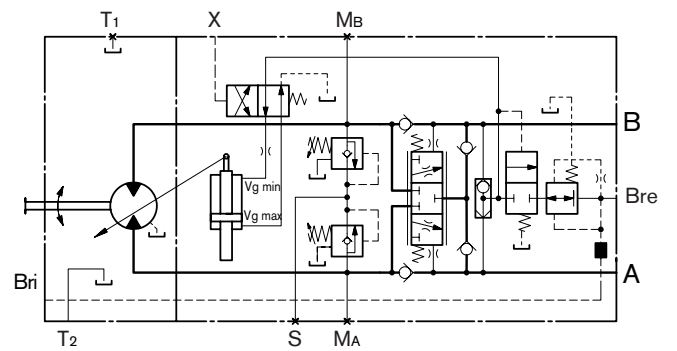
Before finalizing your design, please request approved installation drawing. Dimensions in mm

A6VE...HA3...221 (Brake release via internal boring)

(port X open at HA3T)



A6VE...HZ3...222 (Brake release via external piping)



Flushing and Boost Pressure Valve

Before finalizing your design, please request approved installation drawing. Dimensions in mm

The flushing and boost pressure valve is used to remove heat from the closed circuit and to ensure that a minimum charge pressure is present (opening pressure 16 bar, fixed; note when setting primary valve). A side effect is flushing of the case.

Warm pressure fluid is removed from the relevant low pressure side into the motor case. This is then fed into the reservoir, together with the leakage fluid. The pressure fluid drawn out of the closed circuit in this way has to be replaced by cooled oil that is pumped in by the charge pump.

In the open circuit, the flushing and boost pressure valve is used solely to flush the case from the return line.

The valve is fitted to the variable displacement motor (or integrated into the servo unit, depending on the type of control and the size).

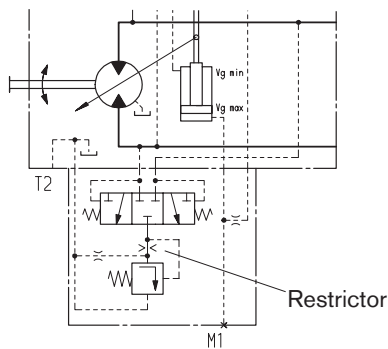
Restrictors can be used to adjust the flow as required.

Standard flow at low pressure $\Delta p_{ND} = 25$ bar

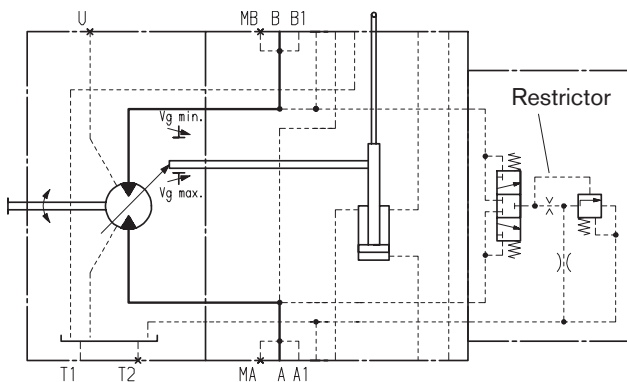
Size	Quantity	Mat.-no. of restrictor
28, 55	3,5 L/min	R909651766
80	5 L/min	R909419695
107	8 L/min	R909419696
160	10 L/min	R909419697
250	10 L/min	on request

For sizes 28 to 160, restrictors for flows of 3,5 - 10 L/min can be supplied. In the case of non-standard flows, please specify the restrictor you require when placing your order. The flushing flow without orifice is approx. 12 to 14 L at low-pressure $\Delta p_{ND} = 25$ bar.

Sizes 28...160

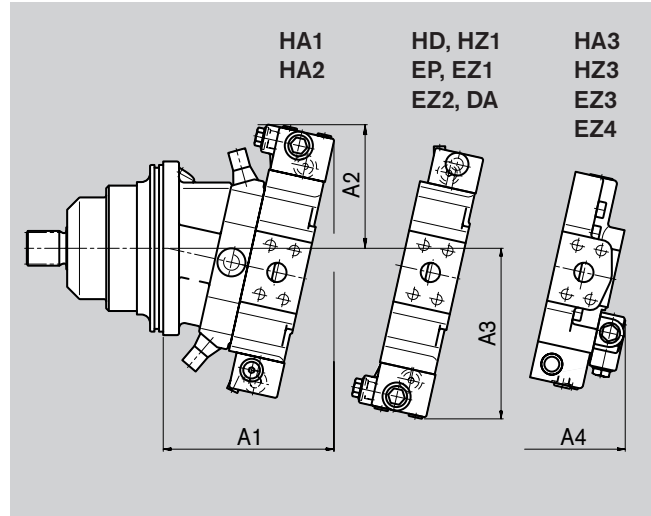


Sizes 250



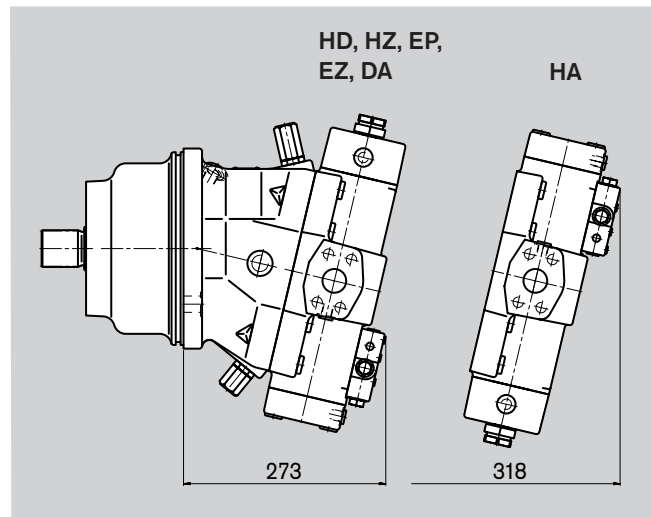
Unit dimensions

Sizes 28...160



Size	A1	A2	A3	A4
28	152	125	161	—
55	182	133	176	176
80	192	141	194	176
107	203	144	200	187
160	245	154	220	—

Size 250



Speed Measurement

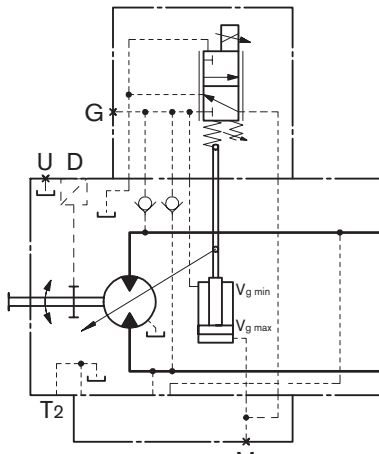
Version „F“ (sizes 28...160) prepared for speed measurement

The A6VE...F version (“prepared for speed measurement” without sensor) have teeth on the drive shaft.

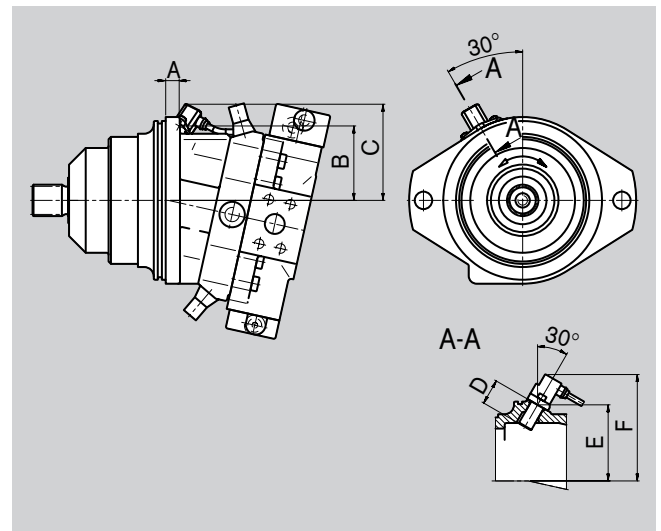
The rotating, toothed drive shaft generates a signal in proportion to the speed. The signal is picked up by a sensor and forwarded for evaluation.

The Version F is suitable to be build-on to HDD hall effect speed sensor (see RE 95135). The HDD sensor is flange mounted with two locking screws at the especially planed port. The standard connection is plugged with a compression-proof flange cover. We recommend ordering the A6VE variable displacement motor with fitted sensor. The ordering code for the sensor must be specified separately..

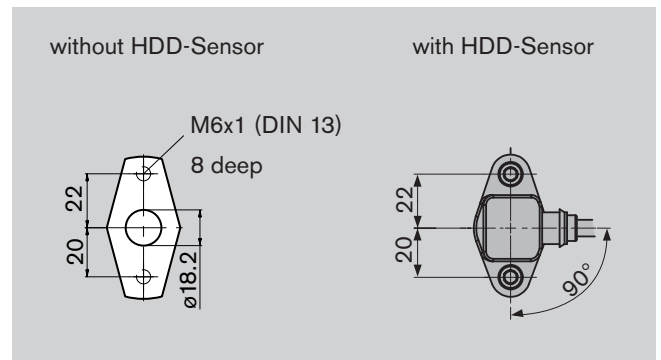
Circuit diagram A6VE 28...160



Unit dimensions



Detail X



Size	28	55	80	107	160
Number of teeth	40	54	58	67	75
A	20,7	25,8	16,8	14,7	28,3
B	59,8	72,2	75,4	83,1	90,4
C	97,9	110,3	113,5	121,2	128,5
D	32	32	32	32	32
E	69±0,1	83,4±0,1	87,1±0,1	95,9±0,1	104,4±0,1
F	107,3	121,7	124,4	133,2	141,7

Suitable speed sensor: size 28...160: HDD.L32../20 (see RE 95 135)

Before finalizing your design, please request approved installation drawing. Dimensions in mm

Connectors for Solenoid (for EP, EZ only)

Before finalizing your design, please request approved installation drawing. Dimensions in mm

DEUTSCH DT04-2P-EP04, 2-pin

injection molded, without bidirectional quenching diode

(for EP, EZ1/2) _____ P

with lead, without bidirectional quenching diode

(for EZ3/4) _____ T

Type of protection to DIN/EN 60529: IP67 and IP69K

Mating connector

DEUTSCH DT06-2S-EP04

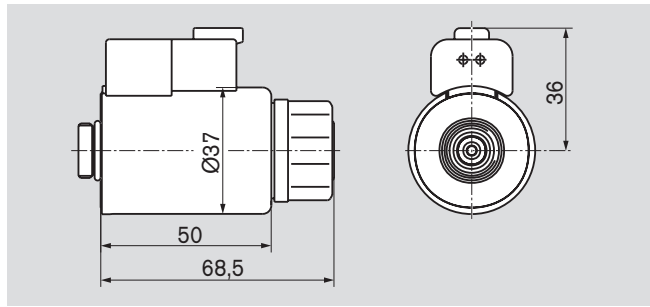
Rexroth Mat.-no. R902601804

comprising:

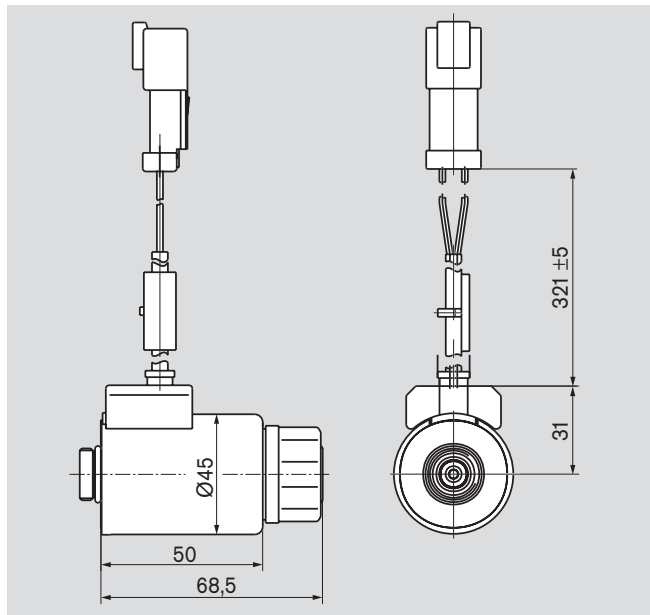
- | | | |
|-------------------|----------------|----------------|
| - 1 case _____ | DT-designation | DT06-2S-EP04 |
| - 1 wedge _____ | | W2S |
| - 2 sockets _____ | | 0462-201-16141 |

The mating connector is not included in supply. It can be supplied by Rexroth on request.

injection molded, without bidirectional quenching diode __P



with lead, without bidirectional quenching diode _____ T



Installation and Commissioning Notes

General

The motor case must be completely filled up with hydraulic fluid during startup and during operation (filling the case chamber). The motor must be started up at low speed and no load until the system has been bled completely.

If stopped for an extended period, fluid may drain out of the case through the working lines. When restarting, make sure that the case contains sufficient fluid.

The case drain inside the case chamber must be drained off to the reservoir through the highest case drain port.

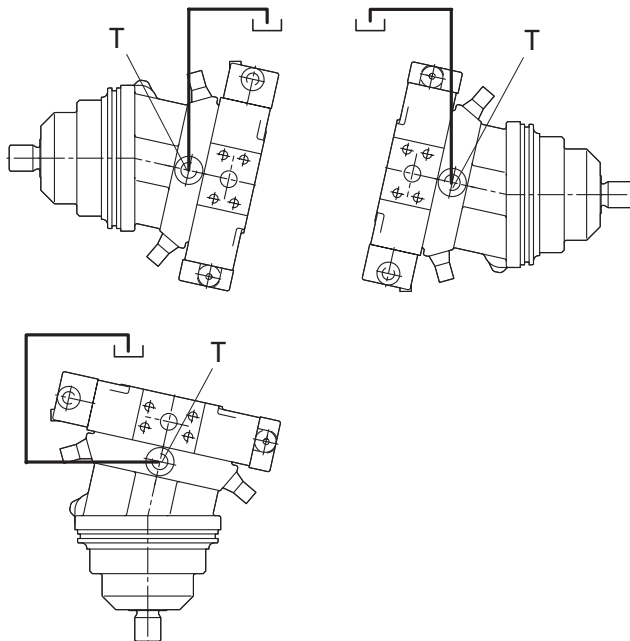
Installation position

Shaft horizontal and shaft downwards. Shaft upwards is not permitted!

Installation below the reservoir

Motor below minimum fluid level in reservoir (standard)

- Fill axial piston motor before startup via the highest case drain port
- Run the motor at low speed until the system is bled completely (bleed through service line port A, B if tubing is long)
- Minimum immersion depth of case drain line in reservoir: 200 mm (relative to the min. fluid level in the reservoir)
- Bleed the A6VE variable displacement motor in a closed circuit:
 - via port G
 - no bleeding required if flushing valve fitted

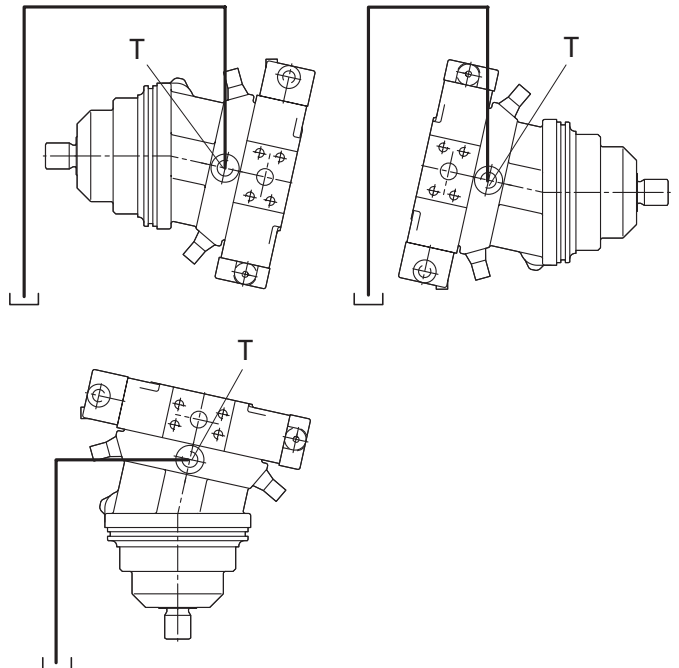


Installation above the reservoir

Motor above minimum fluid level in reservoir

- Proceed in same way as below the reservoir installation
- Additional measures for installation positions „shaft horizontal“

If stopped for an extended period, fluid may drain out of the case chamber through the working lines (air enters through the shaft seal). The bearings will therefore not be properly lubricated when the motor is started up again. Fill the axial piston unit before restarting via the highest case drain port.



Project Sheet

for variable motor A6VE with Integral Counterbalance Valve

3. Hydraulic motor

Type code as to RE 91606 _____

Control device: 2-step proportional

Input flow/motor $q_{V \max} =$ _____ l/min

Displacement/motor $V_{g \min} =$ _____ cm³/rpm $V_{g \max} =$ _____ cm³/rpm

Necessary min. boost pressure (self suction speed at n_{\max}) $p_{\min} =$ _____ bar

Secondary relief valves: pressure setting $p_{\max} =$ _____ bar

Parking brake: no yes release pressure range _____ bar up to _____ bar

Brake lifting internal (Bri) external (Bre) separate by pilot pressure

4. Track drive gear box

Supplier/Type _____

Gear ratio $i =$ _____ Sprocket diameter $d =$ _____ m

Additional informations _____

Comissioned by: _____
 (Name) (Signature)

Modifications

at the prototype: _____

at the hydraulic system: _____

Release

Rexroth: _____
 (Date) (Name) (Signature)

Customer: _____
 (Date) (Name) (Signature)

Type-code of the motor

to RE 91606 A6VE /63W-V 22

Rexroth-Material-no. (fixing after receipt of order): _____

General Notes

- The A6VM motor is designed to be used in open and closed circuits.
- Project planning, assembly, and startup of the motor require the involvement of trained personnel.
- The working and functional ports are only designed to accommodate hydraulic piping.
- Tightening torques:
 - The tightening torques specified in this data sheet are maximum values and may not be exceeded (maximum value for screw thread). Manufacturer specifications for the max. permissible tightening torques of the used fittings must be observed!
 - For DIN 13 fastening screws we recommend checking the tightening torque individually according to VDI 2230 Edition 2003.
- The housing temperature rises during and shortly after operation. Take suitable safety precautions (e.g. wear protective clothing).
- The data and information contained herein must be adhered to.

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Subject to change.